

The Load Balancing Optimization of Telecommunication Networks

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Introduction

Single path routing

- Capacitated telecommunications network

Introduction

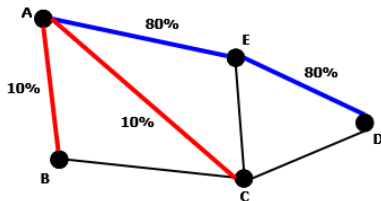
Single path routing

- Capacitated telecommunications network
- Traffic commodities are to be supported by the network
 - single path routing

Introduction

Single path routing

- Capacitated telecommunications network
- Traffic commodities are to be supported by the network
 - single path routing
- Example:
 - Links have capacity 100 Mbps
 - Commodity A-D has demand 80 Mbps
 - Commodity B-C has demand 10 Mbps



Introduction

Network load balancing

- Aim: commodities are to be routed such that network link load is optimized

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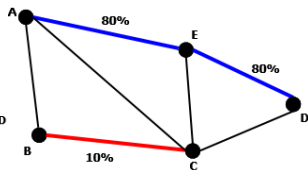
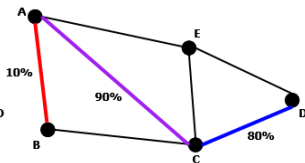
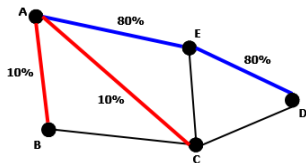
Network load balancing

- Aim: commodities are to be routed such that network link load is optimized
 - minimize the worst link load
 - minimize the second worst link load, guaranteeing that the worst link load is optimized
 - minimize the third link load, guaranteeing that the two worst link loads are optimized
 - ...

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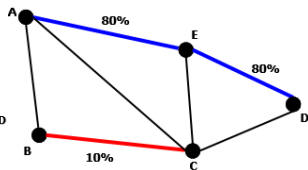
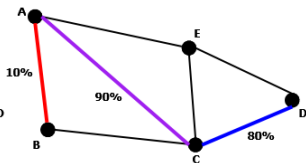
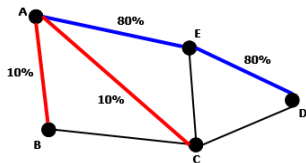
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↪ Network robustness to unpredictable traffic demand growth

Network Load Balancing Optimization

Mathematical formulation

Parameters

- $G(N, A)$
- $c_{\{ij\}}$ capacity of edge $\{i, j\} \in A$
- K set of commodities
 - each commodity $k \in K$ is characterized by its origin node o_k , its destination node d_k and its demand $b_k > 0$
- P_k set of candidate paths for commodity $k \in K$
- $\delta_{\{ij\}}^{pk}$ binary parameter
 - indicates if edge $\{i, j\}$ is in path $p \in P_k$

Network Load Balancing Optimization

Mathematical formulation

Decision variables

- $\mu_{\{ij\}} \in [0, 1]$ – load in edge $\{i, j\} \in A$
- $\varphi_k^p \in \{0, 1\}$ – indicates if candidate $p \in P_k$ is chosen as the path for routing $k \in K$

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Constraints

$$\sum_{p \in P_k} \varphi_k^p = 1 \quad \forall k \in K \quad (1)$$

$$\sum_{k \in K} \sum_{p \in P_k} b_k \delta_{\{ij\}}^{pk} \varphi_k^p = c_{\{ij\}} \mu_{\{ij\}} \quad \forall \{i, j\} \in A \quad (2)$$

$$\mu_{\{ij\}} \in [0, 1], \varphi_k^p \in \{0, 1\} \quad (3)$$

Network Load Balancing Optimization

Mathematical formulation

Optimization Objective

- Minimize worst link load; minimize second worst link load without jeopardizing the worst link load; minimize third worst link load without jeopardizing the two worst link loads; ...

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$$\boldsymbol{\mu} = (\mu_{\{ij\}} : \{i, j\} \in A)$$

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$[\boldsymbol{\mu}]$ is the vector obtained from $\boldsymbol{\mu}$ by rearranging its elements in non-increasing order $\Rightarrow [\boldsymbol{\mu}]_l$ is the l^{th} element of $[\boldsymbol{\mu}]$

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$$\mathbf{lexmin} [\boldsymbol{\mu}]$$

s.t.

$$(1) - (3)$$

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\hookrightarrow Vector $\mathbf{a} = (a_1, \dots, a_m)$ is lexicographically smaller than $\mathbf{b} = (b_1, \dots, b_m)$ if $a_1 < b_1$ or if there exists $k \in \{1, \dots, m-1\}$ such that $a_i = b_i$ for $i \leq k$ and $a_{k+1} < b_{k+1}$

$(1, 3, 2)$ is lexicographically smaller than $(1, 5, 1)$

Network Load Balancing Optimization

Solution approach

- Non-linear problem \Rightarrow can be solved as a sequence of MILPs

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- \Downarrow
- Hybridization of column generation and metaheuristics

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- Hybridization of column generation and metaheuristics
- \hookrightarrow Hybrid CG and GRASP+PR

Hybrid CG and GRASP+PR

Heuristic proposal

- LP column generation (CG) for the load balancing problem
 - set of paths for each commodity $k \in K$

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↪ Search space constrained to paths obtained by CG

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Heuristic proposal

- P = linear relaxation of the load balancing problem
- Ω = search space

Hybrid CG and GRASP+PR

Heuristic proposal

- $P =$ linear relaxation of the load balancing problem
 - $\Omega =$ search space
- 1 $\Phi \leftarrow \text{CG}(P)$
 - 2 $\Omega \leftarrow \Phi$
 - 3 **while** time $<$ *MaxTime* **do**
 - 4 $[\mu] \leftarrow \text{GRASP+PR}(\Omega)$
 - 5 **end**

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↪ If Φ does not have good quality paths \Rightarrow add new paths to the search space

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Heuristic proposal: add new paths

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- 5 $P' \leftarrow \text{Perturbation}([\mu], [\eta])$
- 6 $\Phi \leftarrow \text{CG}(P', \Omega)$
- 7 $\Omega \leftarrow \Omega \cup \Phi$
- 8 **end**

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↪ If the search space grows too much, the search can be jeopardized ⇒
remove some paths

Hybrid CG and GRASP+PR

Heuristic proposal: add and remove paths

- Compute number of times each path is used by the local optimum solutions

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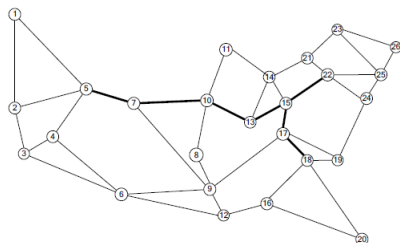
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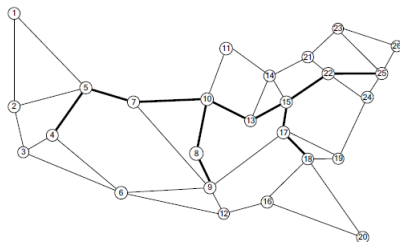
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- 7 $\Phi \leftarrow \text{CG}(P', \Theta)$
- 8 $\Theta \leftarrow \Theta \cup \Phi$
- 9 $\Omega \leftarrow \Omega \cup \Phi \cap E$
- 10 **end**

Computational Results

NSF network configurations



NSF'



NSF''

1 Gbps; 10 Gbps in bold

Computational Results

Instances

- NSF network
 - 26 nodes; 42 links

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- Half of each group have 325 commodities (H) and half have 190 commodities (L)

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Instances

- NSF network
 - 26 nodes; 42 links
- 24 instances:
 - 12 NSF' instances; 12 NSF'' instances
- For each instance a demand matrix was randomly generated
 - emulate different possible real scenarios
- Half of each group have 325 commodities (H) and half have 190 commodities (L)
- Applying CG to the linear relaxation of the load balancing problem:
 - for each instance, the number of paths generated on average per commodity is ≈ 4

Computational Results

Integer RMP

- Solve load balancing problem only with the paths given by the LP

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- Group G:
 - 4 NSF' instances and 6 NSF'' instances
 - half of these instances are of group H
 - at least 3 worst loads were solved and are optimal
 - integer RMP values coincide with LP values

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- Group B:
 - all the other cases
 - the worst load value does not coincide with the LP value
 - for 2 NSF' instances and 2 NSF'' instances the worst load was not even solved within the timelimit
 - may be optimal or not

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 - may be optimal or not

↪ The LP paths contain near optimal solutions for group G

Computational Results

Hybrid CG and GRASP+PR

Search space is not modified (no paths are added):

- Results between PR with incumbent (elite size = 1) and PR with elite list

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- Elite list: size = 20; distance = 30%
- Timelimit = 60 seconds; 10 runs for each instance and PR case
- PR with incumbent:
 - for instances of group G the solutions are of good quality \Rightarrow almost always the 3 worst link loads are optimal

Computational Results

Hybrid CG and GRASP+PR

- PR with elite list:

Instance Sets	Improvement
Global	38.1%
B	56.4%
G	12.8%
H	56.4%
L	17.4%

Computational Results

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- PR with elite list:

Instance Sets	Improvement
Global	38.1%
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- ↪ Overall improvement using elite list
- ↪ Improvement is more significant for groups B and H
- ↪ Average occupancy of elite list is between 4 and 5 \Rightarrow PR does not penalize performance

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Search space is modified (new paths added and/or some paths removed):

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- Perturbed problem P_2 assumes that the worst link load of the incumbent that differs from the LP value is optimal, and aims at lowering the next worst link load

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Computational Results

Hybrid CG and GRASP+PR

Sets	P_1 without exclusion of paths		P_1 with exclusion of paths	
	Modifications	Improvement	Modifications	Improvement
Global	7.2	63.2%	7.1	70.3%
B	6.3	56.4%	6.4	56.4%
G	8.6	77.8%	8.0	85.7%
H	6.7	43.9%	6.2	56.4%
L	7.8	85.7%	7.9	85.7%

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G	8.6	77.8%	8.0	85.7%
H	6.7	43.9%	6.2	56.4%
L	7.8	85.7%	7.9	85.7%

- ↪ Number of added paths does not increase significantly the size of the restricted search space
- ↪ Number of removed paths is of the same order of magnitude of the number of added paths

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H	6.7	43.9%	6.2	56.4%
L	7.8	85.7%	7.9	85.7%

- ↪ Number of added paths does not increase significantly the size of the restricted search space
- ↪ Number of removed paths is of the same order of magnitude of the number of added paths
- ↪ Adding paths using P_1 shows improvement; slightly better performance when exclusion of paths is used
- ↪ Significant improvements for groups G and L

Computational Results

Hybrid CG and GRASP+PR

P_2 :

- ↪ Number of modifications of P_2 similar to P_1
- ↪ P_2 adds much less paths and excludes much more paths \Rightarrow the restricted search space decreases in size
- ↪ P_2 shows slight improvement when exclusion of paths is used
- ↪ P_2 performs worse than P_1

Computational Results

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 - ↪ P_2 performs worse than P_1
- ⇓
- P_1/P_2 combined version

Computational Results

Hybrid CG and GRASP+PR

Sets	P_1/P_2 without exclusion of paths		P_1/P_2 with exclusion of paths	
	Modifications	Improvement	Modifications	Improvement
Global	4.9	56.4%	5.0	94.1%
B	4.4	56.4%	4.4	112,5%
G	5.6	50.0%	5.8	70.3%
H	4.8	85.7%	4.8	112.5%
L	5.2	32.6%	5.1	77.8%

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	Modifications	Improvement	Modifications	Improvement
Global	4.9	56.4%	5.0	94.1%
B	4.4	56.4%	4.4	112.5%
G	5.6	50.0%	5.8	70.3%
H	4.8	85.7%	4.8	112.5%
L	5.2	32.6%	5.1	77.8%

- ↪ Significant decrease in the number of modifications of the search space
- ↪ Number of added paths similar to P_1
- ↪ Number of excluded paths significantly lower than P_1
- ↪ Combined performance with path exclusion is the best

Conclusions

Hybrid CG and GRASP+PR applied to network load balancing

- GRASP+PR performed on restricted search space \Rightarrow search is more efficient

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- PR shows improvement when using elite list with a distance large enough \Rightarrow average occupancy of list should be low
 - favors especially instances from groups B and H

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- PR shows improvement when using elite list with a distance large enough \Rightarrow average occupancy of list should be low
 - favors especially instances from groups B and H
- To improve furthermore: add new paths using P_1 and/or P_2
 - P_1 results in overall better solutions especially when some paths are removed
 - overall improvement of 70.3%
 - favors especially instances of groups G and L

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Hybrid CG and GRASP+PR applied to network load balancing

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- To improve furthermore: add new paths using P_1 and/or P_2
 - P_1 results in overall better solutions especially when some paths are removed
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 - P_2 has poor overall performance
 - P_1/P_2 combined version has the best overall performance especially when some paths are removed
 - overall improvement of 94.1%
 - favors significantly all groups especially B and H

Conclusions

Hybrid CG and GRASP+PR: future work

- Apply heuristic proposal to more complex load balancing problems:
 - Load balancing using multiple spanning trees
 - ↪ D. Santos, A. de Sousa, F. Alvelos, M. Pióro, Optimization of Network Load Balancing in Multiple Spanning Tree Routing Networks, Telecommunication Systems Journal, 48(1-2), pp 109-124, Springer, 2011
 - Load balancing with path protection
 - ↪ A. de Sousa, D. Santos, P. Matos and J. Madeira, Load balancing optimization of capacitated networks with path protection, Electronic Notes, 36, pp. 1249-1256, 2010

Conclusions

Hybrid CG and GRASP+PR: SearchCol

- Complementary work to
 - ↪ D. Santos, A. de Sousa, F. Alvelos, M. Pióro, Link Load Balancing Optimization of Telecommunication Networks: a Column Generation based Heuristic Approach, NETWORKS 2010, Warsaw, Poland, September, 2010
 - ↪ F. Alvelos, A. de Sousa, D. Santos, SearchCol: Metaheuristic Search by Column Generation, 7th International Workshop on Hybrid Metaheuristics, Vienna, Austria, October, 2010

SearchCol

Metaheuristic Search by Column Generation

<http://searchcol.dps.uminho.pt>